MOBOT® FlatRunner HT (002) mobile robot

A mobile robot used to automate internal transport and transport heavy loads such as pallets or parcels. Automatically moves along the route.

- ► Easy to use Works safely with people while carrying your loads
- ► Increases production efficiency and reduces costs
- ► Automates production lines and intralogistics
- ► Can work with palletizing robots





operating time up to 8 h on a single charge



payload up to 500 kg



Wi-Fi communication



dimensions 1600 x 750 x 239 mm



max speed 3 km/h

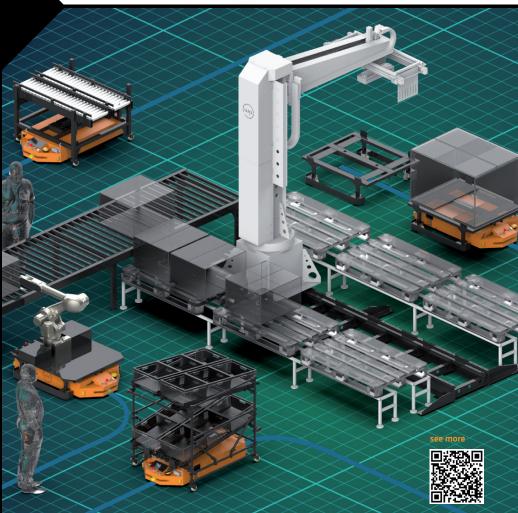


line navigation using the vision system



system of rectactable pins

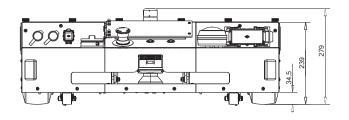
Intended use: transport of heavy loads in industry and logistics

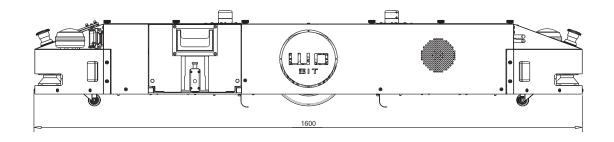


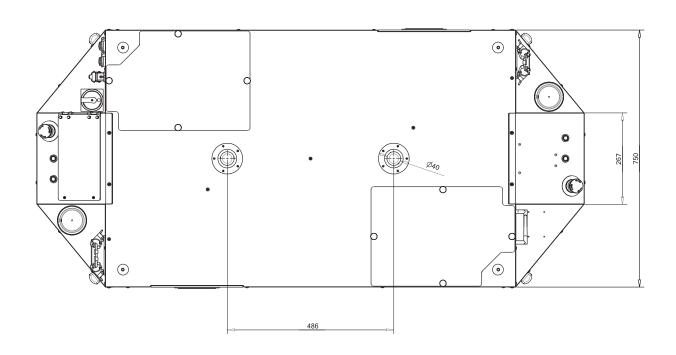


Robot type	MOBOT®AGV FlatRunner HT (002)
Payload and transport method	
Transport method	Cart guided over the robot with the possibility of attaching using two automatic pins
Permissible total weight of the cart with load	500 kg
Power supply	
Manual battery charging connector	YES (24 V DC, max. 30 A)
Automatic battery charging connector	A contact connector mounted on the bottom of the robot enables automatic battery charging during operation
Robot power supply	2 x traction battery 85 Ah /12 V The battery is mounted in a cassette allowing for quick replacement in the robot
Charger	- 30 A / 24 V charger connected manually - Optional charging station with 30A / 24V charger for charging replaceable battery cartridges - Optional contact module for automatic charging
Operating time at full load	~ 8 h
Operating time in standby mode	~ 40 h
Battery charging time	~ 3 h
Speed and performance	
Maximal speed	3 km/h
Nominal power	1200 W
Movement directions	Move forward / backward, turn
Turning radius	The possibility of turning back in place
Maximum surface slope	Robot designed for driving on a flat surface
Navigation	
Navigation	Navigation along the line using vision system
Communication	
Communication	2.4 GHz Wi-Fi, optional 2.4 GHz industrial radio module (RS232)
Communication Connector	2.4 GHz Wi-Fi, optional 2.4 GHz industrial radio module (RS232) - Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power supply output (2A) + 24 VDC power supply output (10 A)
	- Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power
Connector	- Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power
Connector Drive and control	- Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power supply output (2A) + 24 VDC power supply output (10 A)
Connector Drive and control Drive	- Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power supply output (2A) + 24 VDC power supply output (10 A) 2x BLDC motor, wheels diameter 215 mm - 1 x 7 "touch operator panel - 2 x emergency stop - 2 x emergency stop - 2 x emergency stop reset confirmation buttons - 1 x main power switch - 2 x function button - 1x USB connector
Drive and control Drive Control and steering	- Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power supply output (2A) + 24 VDC power supply output (10 A) 2x BLDC motor, wheels diameter 215 mm - 1 x 7 "touch operator panel - 2 x emergency stop - 2 x emergency stop - 2 x emergency stop reset confirmation buttons - 1 x main power switch - 2 x function button - 1x USB connector
Drive and control Drive Control and steering Sensors	- Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power supply output (2A) + 24 VDC power supply output (10 A) 2x BLDC motor, wheels diameter 215 mm - 1 x 7 "touch operator panel - 2 x emergency stop - 2 x emergency stop reset confirmation buttons - 1 x main power switch - 2 x function button - 1 x USB connector - 1 x Ethernet connector
Drive and control Drive Control and steering Sensors Sensors	- Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power supply output (2A) + 24 VDC power supply output (10 A) 2x BLDC motor, wheels diameter 215 mm - 1 x 7 "touch operator panel - 2 x emergency stop - 2 x emergency stop reset confirmation buttons - 1 x main power switch - 2 x function button - 1 x USB connector - 1 x Ethernet connector - 2 x vision system for tracking the line - 2 x 2D laser scanner with security function - 2 x light and sound signaling devices - 2 x speaker (voice / music messages)
Drive and control Drive Control and steering Sensors Sensors Signaling	- Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power supply output (2A) + 24 VDC power supply output (10 A) 2x BLDC motor, wheels diameter 215 mm - 1 x 7 "touch operator panel - 2 x emergency stop - 2 x emergency stop reset confirmation buttons - 1 x main power switch - 2 x function button - 1 x USB connector - 1 x Ethernet connector - 2 x vision system for tracking the line - 2 x 2D laser scanner with security function - 2 x light and sound signaling devices - 2 x speaker (voice / music messages)
Connector Drive and control Drive Control and steering Sensors Sensors Signaling Environment	- Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power supply output (2A) + 24 VDC power supply output (10 A) 2x BLDC motor, wheels diameter 215 mm - 1 x 7 "touch operator panel - 2 x emergency stop - 2 x emergency stop reset confirmation buttons - 1 x main power switch - 2 x function button - 1 x USB connector - 1 x Ethernet connector - 2 x vision system for tracking the line - 2 x 2D laser scanner with security function 2 x light and sound signaling devices - 2 x speaker (voice / music messages) - 4 x direction indicator
Drive and control Drive Control and steering Sensors Sensors Signaling Environment Operating temperature range	- Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power supply output (2A) + 24 VDC power supply output (10 A) 2x BLDC motor, wheels diameter 215 mm - 1 x 7 "touch operator panel - 2 x emergency stop - 2 x emergency stop reset confirmation buttons - 1 x main power switch - 2 x function button - 1 x USB connector - 1 x Ethernet connector - 2 x vision system for tracking the line - 2 x 2D laser scanner with security function - 2 x light and sound signaling devices - 2 x speaker (voice / music messages) - 4 x direction indicator
Drive and control Drive Control and steering Sensors Sensors Signaling Environment Operating temperature range Humidity range	- Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power supply output (2A) + 24 VDC power supply output (10 A) 2x BLDC motor, wheels diameter 215 mm - 1 x 7 "touch operator panel - 2 x emergency stop - 2 x emergency stop - 1 x main power switch - 2 x function button - 1 x USB connector - 1 x Ethernet connector - 2 x vision system for tracking the line - 2 x 2D laser scanner with security function - 2 x light and sound signaling devices - 2 x speaker (voice / music messages) - 4 x direction indicator 5 ÷ 45 °C < 80 %, no condesation
Drive and control Drive Control and steering Sensors Sensors Signaling Environment Operating temperature range Humidity range Protection degree	- Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power supply output (2A) + 24 VDC power supply output (10 A) 2x BLDC motor, wheels diameter 215 mm - 1 x 7 "touch operator panel - 2 x emergency stop - 2 x emergency stop reset confirmation buttons - 1 x main power switch - 2 x function button - 1 x USB connector - 1 x Ethernet connector - 2 x vision system for tracking the line - 2 x 2D laser scanner with security function 2 x light and sound signaling devices - 2 x speaker (voice / music messages) - 4 x direction indicator 5 ÷ 45 °C < 80 %, no condesation IP30
Drive and control Drive Control and steering Sensors Sensors Signaling Environment Operating temperature range Humidity range Protection degree The intensity of external light	- Ethernet RJ45 - communication with PC, MODBUS TCP / IP - 18 pin connector, E-Stopx2, Reset, RS485 (Modbus RTU), CANopen, 2 x input, 24 VDC power supply output (2A) + 24 VDC power supply output (10 A) 2x BLDC motor, wheels diameter 215 mm - 1 x 7 "touch operator panel - 2 x emergency stop - 2 x emergency stop reset confirmation buttons - 1 x main power switch - 2 x function button - 1 x USB connector - 1 x Ethernet connector - 2 x vision system for tracking the line - 2 x 2D laser scanner with security function - 2 x light and sound signaling devices - 2 x speaker (voice / music messages) - 4 x direction indicator 5 ÷ 45 °C < 80 %, no condesation IP30









 $\ensuremath{\mathsf{AII}}$ dimensions are approximate values and can change.













Accessories

Transport cart for pallets

The transport cart is suitable for transporting standard EURO pallets. On the bottom of the cart, is located a guide that enables attach the robot through its hitch pins.

Cart with gravity roller conveyor

The gravity roller feed system allows to transport and automatically receive and transfer goods placed in the cuvettes. The system consists of a movable conveyor attached to the mobile robot using pins and a fixed conveyor permanently attached to the ground.

When the conveyors have docked, the latches on both conveyors are automatically released and shift the load on them.

Cart with automatic rollers

Designed for transporting various types of containers, packages. The system consists of an automatic roller feeder attached to the mobile robot using its mandrels. The rollers are powered by powered engines from robot batteries and ensure fast and smooth flow of goods.

Robotic arm adapter

It is a flexible solution ensuring maximum mobility and autonomous robot operation that optimizes production processes. The adapter is equipped with four additional wheels to ensure perfect stability, as well as a housing for a robot controller.

Charging station

Cart trolley with batteries

